

EQUATIONS

<p>Uncertainty</p> <ul style="list-style-type: none"> • $u_p = (\delta A / A) \times 100\%$ <p>Kinematics</p> <ul style="list-style-type: none"> • $\Delta x = x_f - x_0$ • $\Delta t = t_f - t_0$ • $v = \Delta x / \Delta t = (x_f - x_0) / (t_f - t_0)$ • $a' = \Delta v / \Delta t = (v_f - v_0) / (t_f - t_0)$ • $x = x_0 + v' t$ • $v = (v_0 + v) / 2$ • $x = x_0 + v_0 t + \frac{1}{2} a t^2$ • $v^2 = v_0^2 + 2 a (x - x_0)$ <p>Two-Dimensional Kinematics</p> <ul style="list-style-type: none"> • $a^2 + b^2 = c^2$ • $c = \sqrt{(a^2 + b^2)}$ • $\mathbf{A} - \mathbf{B} = \mathbf{A} + (-\mathbf{B})$ • $\mathbf{A}_x + \mathbf{A}_y = \mathbf{A}$ • $A_x = A \cos \theta$ • $A = \sqrt{(A_x^2 + A_y^2)}$ • $R_x = A_x + B_x$ • $h = v_{0y}^2 / 2g$ • $R = v_0^2 \sin 2\theta_0 / g$ <p>Dynamics - Force and Newton's laws of Motion</p> <ul style="list-style-type: none"> • $\mathbf{a} = \mathbf{F}_{net}/m$ • $w = mg$ <p>Applications of Newton's Laws</p> <ul style="list-style-type: none"> • $f_s \leq \mu_s N$ • $f_k = \mu_k N$ • $F_D = C \rho A v^2$ • $v = \sqrt{(2mg/\rho C A)}$ • $F_s = 6\pi r \eta v$ • $F = k \Delta L$ • $F/A = Y (\Delta L/L_0)$ • $\Delta x = (1/S) (F/A) L_0$ • $\Delta V = (1/B) (F/A) V_0$ <p>Uniform Circular Motion and Gravitation</p> <ul style="list-style-type: none"> • $\Delta\theta = \Delta s/r$ • $\omega = \Delta\theta/\Delta t$ • $a_c = v^2/r$ • $F = G m M / r^2$ • $g = GM/r^2$ • $T_1^2/T_2^2 = r_1^3/r_2^3$ <p>Work Energy and Energy Resources</p> <ul style="list-style-type: none"> • $W = F d \cos \theta$ • $W_{net} = \frac{1}{2} m v^2 - \frac{1}{2} m v_0^2$ • $K = \frac{1}{2} m v^2$ • $W = F d = m g h$ • $U_g = m g h$ • $K_i + U_i = K_f + U_f$ • $K_i + U_i + W_{nc} + O_i = K_f + U_f + O_f$ • $E_{eff} = W_{out} / E_{in}$ • $P = W/t = E/t$ <p>Linear Momentum and Collisions</p> <ul style="list-style-type: none"> • $p = m v$ • $F_{net} = \Delta p / \Delta t$ • $\Delta p = F_{net} \Delta t$ • $(p_1 + p_2)_f = (p_1 + p_2)_i = \text{constant}$ • $m_1 v_1 = m_1 v'_1 \cos \theta_1 + m_2 v'_2 \cos \theta_2$ • $m_1 v_1 = m_1 v'_1 \sin \theta_1 + m_2 v'_2 \sin \theta_2$ • $a = [(v_e/m) (\Delta m_b / \Delta t)] - g$ 	<p>Statics and Torque</p> <ul style="list-style-type: none"> • $\tau = r F \sin \theta$ • $A_M = F_o / F_i = l_i / l_o \quad l_i F_i = l_o F_o$ <p>Rotational Motion and Angular Momentum</p> <ul style="list-style-type: none"> • $\omega = \Delta\theta/\Delta t$ • $v = r \omega \quad \omega = v/r$ • $\alpha = \Delta\omega/\Delta t \quad \alpha = a_t / r$ • $a_t = r \alpha$ • $\theta = \theta_0 + \omega t$ • $\omega = \omega_0 + \alpha t$ • $\theta = \omega_0 t + \frac{1}{2} \alpha t^2$ • $\omega^2 = \omega_0^2 + 2 \alpha \theta$ • $I = \sum m r^2$ • $\tau_{net} = I \alpha \quad \alpha = \tau_{net} / I$ • $K_{rot} = \frac{1}{2} I \omega^2$ • $L = I \omega$ • $\tau = \Delta L / \Delta t$ • $I \omega = I' \omega'$ <p>Fluids</p> <ul style="list-style-type: none"> • $P = h \rho g$ • $F_B = w_f$ • $Q = V/t = A d/t = A(d/t) = A v$ • $A_1 v_1 = A_2 v_2$ • $P_1 + (\frac{1}{2}) \rho v_1^2 + \rho g h_1 = P_2 + (\frac{1}{2}) \rho v_2^2 + \rho g h_2$ • $E/t = P Q$ • $\eta = F L / v A$ • $R = 8 \eta l / \pi r^4$ • $Q = (P_2 - P_1) \pi r^4 / 8 \eta l$ • $N_R = 2 \rho v r / \eta$ <p>Temperature Kinetic Theory and Gas laws</p> <ul style="list-style-type: none"> • $T_C = (5/9) [T_F - 32^\circ]$ • $T = T_C + 273.15$ • $\Delta L = \alpha L \Delta T$ • $P V = N k T$ • $k = 1.38 \times 10^{-23} \text{ J/K}$ • $N_A = 6.02 \times 10^{23} \text{ mol}^{-1}$ • $P V = n R T$ • $R = N_A k = 8.31 \text{ J/mol K}$ • $P = F/A$ • $v_{rms} = \sqrt{(v^2)_{avg}}$ • $K_{ave} = (3/2) k_B T$ <p>Heat and Heat Transfer Methods</p> <ul style="list-style-type: none"> • $Q = m c \Delta T$ • $Q = m L_f \quad Q = m L_v$ • $Q/t = k A (T_2 - T_1)/d$ • $Q/t = \sigma e A T^4$ • $Q_{net}/t = \sigma e A (T_2^4 - T_1^4)$ <p>Thermodynamics</p> <ul style="list-style-type: none"> • $\Delta U = Q - W$ • $E_{eff} = W/Q_h \quad W = Q_h - Q_c$ • $E_{eff} = (Q_h - Q_c)/Q_h = 1 - (Q_c/Q_h) \quad E_{effc} = 1 - (T_c/T_h)$ • $Q_c/Q_h = T_c/T_h \quad C_{PH} = Q_h/W_{in} = T_h/(T_h - T_c)$ • $C_{PC} = Q_c/W_{in} = T_c/(T_h - T_c) \quad C_{PC} = Q_c/W_{in} = T_c/(T_h - T_c)$ • $\Delta S_{rev} = Q/T$ <p>Constants</p> <ul style="list-style-type: none"> • $g = 9.80 \text{ m/s}^2$ • $1 \text{ lb} = 4.44822 \text{ N}$ • $1 \text{ hp} = 746 \text{ W}$ • $1 \text{ atm} = 1.013 \times 10^5 \text{ Pa}$ • $G = 6.67384(80) \times 10^{-11} \text{ N m}^2/\text{kg}^2$ • $1 \text{ kg} = 2.2 \text{ lb}$ • $1 \text{ cal} = 4.184 \text{ J}$ • $1 \text{ m}^3 = 10^3 \text{ L}$
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